## Department of Mechanical and Energy Engineering

## Program of Robotics Engineering for International Students (2022)

## I. Introduction

Robotics Engineering is an interdisciplinary program that integrates the learning of mechanical, electronic, and computer technologies. The aim of the program is to cultivate leading talents with solid scientific foundation, excellent innovative practical ability and broad international vision, who are good at comprehensive application of theories and methods of robotics and related disciplines, and who can solve engineering problems with the latest scientific development for the future. In terms of research, its directions cover industrial robots, robot software, bionic robots, medical robots, field robots, microrobots and emerging frontier areas of science and technology such as artificial intelligence, autonomous system, supporting the national economic development plan and Shenzhen's local informatization, intellectualization and manufacturing comprehensive upgrade.

Academic subject area: Automation; Program code: 080803T

## II. Objectives and Learning Outcomes

## 1. Objectives

This program bases its objectives on the future development of robotics engineering and serves the human resource demand of the field in the background of the national mid and long term development planning. The program is committed to fostering students with a solid scientific foundation, excellent innovation capacity, broad international vision, integrated use of robotics theories and related disciplines, and skills of solving the engineering problems for the future with the latest science development.

## 2. Learning Outcomes

a) Solid and broad basic theoretical knowledge (including mathematics, physics, machinery, automation, electronics, computer, etc.), as well as subject knowledge in robot engineering.
b) Master the robotics theories, research and engineering design methods of robot engineering, and have a good knowledge of engineering technology and frontier development of the industry.

Robotics Engineering is a multidisciplinary and interdisciplinary program and foster its students to become leading cross-disciplinary talents for the future.
c) Develop students with rigorous and practical attitude toward science and research, engagement in pursuing excellence, a strong sense of social responsibility and mission, and good communication skills.
d) Develop students with innovative thinking and the ability to independently identify, understand and solve problems in the real world with the application of robotics via the learning of the program.
e) Develop the international outlook and skills of communication and collaboration with international professionals of the related industry.

## III. Study Length, Degree, and Graduation Requirements

1. Study length: 4 years. The academic credit system of SUSTech allows flexible study years, but not less than 3 years or more than 6 years
2. Degree conferred: Students who complete and meet the degree requirements of the undergraduate program will be awarded a Bachelor's Degree in Engineering.
3. The minimum credit requirement for graduation: 152 credits. The specific requirements are as follows.

|  | Module | Category | Minimum Credit <br> Requirement |
| :---: | :---: | :---: | :---: |
| General Education Courses | Chinese Language and Culture Module | Chinese Language and Culture | 16 |
|  | Arts and Physical Education Module | Physical Education | 4 |
|  |  | Arts | 2 |
|  | Competence Development Module | Computer Programming | 3 |
|  |  | Writing | 2 |
|  |  | Chinese Studies | 2 |
|  |  | Foreign Languages | 14 |
|  | Humanities and Social Sciences Module | Humanities | 6 |
|  |  | Social Sciences |  |
|  | Mathematics and Natural Sciences Module | Mathematics | 12 |
|  |  | Physics | 10 |
|  |  | Chemistry | 3 |
|  |  | Biology | 3 |
|  | Introduction to Majors Module | Introduction to Majors | 2 |
| Major Courses | Major Required Courses | Major Foundational Courses | 26 |
|  |  | Major Core Courses | 20 |
|  |  | Practice-based Learning <br> (Undergraduate Thesis, Internships, <br> Research projects, etc.) | 12 |
|  | Major Elective Courses | Major Elective Courses | 15 |
| Total |  |  | 152 |
| Note: please see the General Education Requirement for more details on Chinese Language and Culture Module, Arts and Physical Education Module, Competence Development Module (Foreign Languages \& Chinese Studies \& Writing) , Humanities and Social Sciences Module, and Introduction to Majors Module. |  |  |  |

## IV. Course Requirements for the Mathematics and Natural Sciences Module and

 Computer Programming| Course | Course Code | Course Name | Credits | Terms | Prerequisite | Dept. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## V. Prerequisites for Major Declaration

| Major <br> Declaration Time | Course Code | Course Name | Prerequisite |
| :---: | :---: | :---: | :---: |
| Declare major at the end of the first academic year | MA101a/ <br> MA117 | Mathematical Analysis I /Calculus I | None |
|  | MA102a/ MA127 | Mathematical Analysis II /Calculus | Mathematical Analysis I/ Calculus I |
|  | PHY101/ <br> PHY105 | General Physics I /College Physics I | None |
|  | PHY102/ <br> PHY106 | General Physics II /College Physics | General Physics I/ College Physics I |
|  | Note: <br> The above courses are required to be completed. In addition, at least one of the following Course Category should be passed: <br> 1. Mathematics: MA107/MA113 Advanced Linear Algebra I / Linear Algebra <br> 2. Physics: PHY104B Experiments of Fundamental Physics. <br> 3. Chemistry: CH103/CH105 General Chemistry / Chemistry: The Central Science. <br> 4. Biology: BIO102B/BIO103 Principles of Biology / Introduction to Life Science. <br> 5. Computer Programming: CS109/CS110/CS111/CS112 Introduction to Computer Programming/ Introduction to Java Programming/ Introduction to C programming/ Introduction to Python Programming Python |  |  |
| Declare major at the end of the second academic year | MA101a/ <br> MA117 | Mathematical Analysis I /Calculus I | None |
|  | MA102a/ <br> MA127 | Mathematical Analysis II /Calculus II | Mathematical Analysis I/ Calculus I |
|  | PHY101/ PHY105 | General Physics I /College Physics I | None |
|  | PHY102/ PHY106 | General Physics II /College Physics II | General Physics I/ College Physics I |
|  | MA107/ <br> MA113 | Advanced Linear Algebra I / Linear Algebra | None |
|  | Note: <br> The above courses are required to be completed. In addition, at least one of the following Course Category should be passed: CS109/CS110/CS111/CS112 Introduction to Computer Programming/ Introduction to Java Programming/ Introduction to C programming/ Introduction to Python Programming Python. |  |  |
| Note: <br> 1. If the number of students entering a major at the end of the first academic year in the department is greater than or equal to the total number of the teaching-research faculty $(\mathbf{P I}) * 2 * 60 \%$, all majors in the department may implement the prerequisites for major declaration at the end of the second academic year. <br> 2. If the number of students entering a major at the end of the first academic year in the department is less than the total number of the teaching-research faculty (PI)*2*60\%, all majors in the department do not implement the prerequisites for major declaration at the end of the second academic year. <br> 3. Suppose the number of students applying for a major at the end of the first academic year exceeds four times the total number of the teaching-research faculty (PI), then the department may select students according to predetermined rules. In principle, the rules set by the department shall examine the students' suitability for the major and not based on weighted GPA (Specific rules shall be set by the department and announced in advance). <br> 4. For departments that do not implement prerequisites for major declaration at end of the second academic year, if the cumulative number of students applying for a major at the end of the second academic year and the number of students who have entered a major at the end of the first academic year exceeds four times the total number of the teaching-research faculty (PI), the department may select students according to predetermined rules. In principle, the rules set by the department shall examine the students' suitability for the major and not based on weighted GPA (Specific rules shall be set by the department and announced in advance). |  |  |  |
|  |  |  |  |
|  |  |  |  |

## VI: Major Course Arrangement

Table 1: Major Required Courses

## Program of Robotics Engineering

| Course <br> Category | Course Code | Course Name | Credits | Practice-based Learning Credits | Terms | Prerequisite | Dept. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 氷。 | ME103 | Awareness <br> Practice of Manufacturing Engineering | 3 | 2 | $\begin{gathered} \text { 1/Summer, 1- } \\ 2 \text { Spring } \\ \text { \&Fall } \end{gathered}$ |  | MEE |
|  | ME102 | CAD and Engineering Drawing | 3 | 1.5 | 2 Spring \&Fall |  | MEE |
|  | EE104 | Fundamentals of Electric Circuits | 2 |  | 2 Spring <br> \&Fall | MA101B, MA113 | EE |
|  | EE205 | Signals and Systems | 3 | 1 | 2/Fall | MA127 | EE |
|  | MAE203B | Engineering <br> Mechanics I - <br> Statics and <br> Dynamics | 3 |  | 2/Fall | MA113 | MAE |
|  | MA212 | Probability and Statistics | 3 | 1 | 2 Spring <br> \&Fall | MA127 | MA |
|  | ME212 | Materials <br> Mechanics in <br> Mechanical <br> Engineering | 3 |  | 2/Fall |  | MEE |
|  | ME307 | Fundamentals of Control Engineering | 3 | 0.5 | 2/Spring | EE104 | MEE |
|  | ME213 | Principles of Machinery | 3 |  | 2/Spring |  | MEE |
|  |  | Total | 26 | 6 |  |  |  |
|  | ME331 | Robot Modeling and Control | 3 |  | 3/Fall | MAE203B | MEE |
|  | ME311 | Mechanical Design | 3 |  | 3/Fall |  | MEE |
|  | ME316 | Machinery and Mechanical Design Labs | 2 | 2 | 3 Spring <br> \&Fall |  | MEE |
|  | ME322 | Robotic Actuation System | 3 | 1 | 3/Fall | MA127 | MEE |
|  | ME323 | Sensing Technologies | 3 | 0.5 | 3/Spring | EE104, EE205 | MEE |
|  | ME333 | Mechatronic Systems | 3 | 1 | 3/Spring | ME331 | MEE |
|  | ME338 | Machine <br> Learning for Engineering | 3 |  | 4/Fall | MA212, <br> CS109/ <br> CS110/ <br> CS111/ <br> CS112, <br> MA107A | MEE |
|  | Total |  | 20 | 4.5 |  |  |  |


|  | ME498 | Senior Project* | 12 | 12 | 4/Spring | MEE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | otal | 12 | 12 |  |  |
| Total |  |  | 58 | 22.5 |  |  |

Table 2: Major Elective Courses
Program of Robotics Engineering

| Course Code | Course Name | Credits | Practice-based <br> Learning <br> Credits | Terms | Prerequisite | Dept. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ME332 | Robot Operating System | 3 | 1 | 2/Spring | CS109/ CS110/ CS111/ CS112/ CS113 | MEE |
| CS205 | C/C++ Program Design | 3 | 1 | 2/Spring |  | CS |
| EE202-17 | Digital Circuits | 3 |  | 2 Spring \&Fall | PHY106 | EE |
| MEE5002 | Fundamentals and practices of project management | 3 |  | 2/Spring |  | MEE |
| EE201-17 | Analog Circuits | 3 |  | 3 Spring \&Fall | $\begin{gathered} \hline \text { PHY106, } \\ \text { EE104 } \\ \hline \end{gathered}$ | EE |
| CS203B | Data Structures and Algorithm Analysis B | 3 | 1 | 3/Fall | CS109 | CS |
| ME315 | Mechanisms and Applications | 3 |  | 3/Fall | $\begin{aligned} & \text { ME212, } \\ & \text { MA113 } \end{aligned}$ | MEE |
| MEE5103 | Walking Robot | 3 | 0.5 | 3/Fall | ME331 | MEE |
| CS308 | Computer Vision | 3 | 1 | 3/Fall |  | CS |
| ME301 | Dynamics and Vibration | 3 | 1 | 3/Spring | $\begin{aligned} & \text { MAE203B, } \\ & \text { MA201b } \end{aligned}$ | MEE |
| ME302 | Fundamentals of Manufacturing | 3 |  | 3/Spring | ME103 | MEE |
| ME313 | Product Design Practice | 3 | 1 | 3/Spring | ME213/ <br> ME311/ <br> ME316/ <br> ME331 | MEE |
| ME314 | Finite Element Theory and Its Engineering Applications | 3 |  | 3/Spring | $\begin{aligned} & \text { ME212, } \\ & \text { MA113 } \end{aligned}$ | MEE |
| ME336 | Collaborative Robot Learning | 3 | 1 | 3/Spring | ME331 | MEE |
| MEE5108 | Microrobotics | 3 |  | 3/Spring | ME307 | MEE |
| MEE5116 | Advanced Kinematics and Dynamics of Mechanisms | 3 |  | 3/Spring | ME331 | MEE |
| CS401 | Intelligent Robotics | 3 | 1 | 3/Spring | $\begin{gathered} \text { MA212, } \\ \text { CS102B, } \\ \text { CS203 } \end{gathered}$ | CS |
| ME424 | Modern Control and Estimation | 3 |  | 4/Fall | ME307 | MEE |
| MEE5105 | Fundamentals of Engineering Optimization | 3 |  | 4/Fall | MA127, MA113 | MEE |
| MEE5107 | Microfabrication and Microsystems | 3 |  | 4/Fall | ME307 | MEE |
| MEE5110 | Soft Robotics | 3 |  | 4/Fall | ME213 | MEE |
| MEE5115 | Autonomous Robotic Systems | 3 |  | 4/Fall | MA113, MA212 | MEE |
|  | Total | 66 | 8.5 |  |  |  |

## Note:

1. The minimum requirement for graduation in this module is 15 credits. In addition, the courses starting with MEE can't be more than 6 credits.
2. Major elective courses selected by a student during any specific semester may be changed according to the loading situation.
3. The number and contents of major elective courses offered by the department may be adjusted according to the development of curriculum construction.

Table 3: Overview of Practice-based Learning
Program of Robotics Engineering

| Course Code | Course Name | Credits | Practice-based <br> Learning <br> Credits | Terms | Prerequisite | Dept. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ME103 | Awareness Practice of Manufacturing Engineering | 3 | 2 | 1/Summer, 1-2 <br> Spring \&Fall |  | MEE |
| ME102 | CAD and <br> Engineering Drawing | 3 | 1.5 | 2 Spring \&Fall |  | MEE |
| EE205 | Signals and Systems | 3 | 1 | 2/Fall | MA127 | EE |
| MA212 | Probability and Statistics | 3 | 1 | 2 Spring \&Fall | MA127 | MA |
| ME307 | Fundamentals of Control Engineering | 3 | 0.5 | 2/Spring | EE104 | MEE |
| ME316 | Machinery and Mechanical Design Labs | 2 | 2 | 3 Spring \&Fall |  | MEE |
| ME322 | Robotic Actuation System | 3 | 1 | 3/Fall | MA127 | MEE |
| ME323 | Sensing <br> Technologies | 3 | 0.5 | 3/Spring | EE104, EE205 | MEE |
| ME333 | Mechatronic Systems | 3 | 1 | 3/Spring | ME331 | MEE |
| ME332 | Robot Operating System | 3 | 1 | 2/Spring | $\begin{array}{\|c\|} \hline \text { CS109/ CS110/ } \\ \text { CS111/ } \\ \text { CS112/ } \\ \text { CS113 } \\ \hline \end{array}$ | MEE |
| CS205 | C/C++ Program <br> Design | 3 | 1 | 2/Spring |  | CS |
| CS203B | Data Structures and Algorithm Analysis B | 3 | 1 | 3/Fall | CS109 | CS |
| MEE5103 | Walking Robot | 3 | 0.5 | 3/Fall | ME331 | MEE |
| CS308 | Computer Vision | 3 | 1 | 3/Fall |  | CS |
| ME301 | Dynamics and Vibration | 3 | 1 | 3/Spring | $\begin{aligned} & \text { MAE203B, } \\ & \text { MA201b } \end{aligned}$ | MEE |
| ME313 | Product Design Practice | 3 | 1 | 3/Spring | ME213/ ME311 / ME316/ ME331 | MEE |
| ME336 | Collaborative Robot Learning | 3 | 1 | 3/Spring | ME331 | MEE |
| CS401 | Intelligent Robotics | 3 | 1 | 3/Spring | MA212, CS102B, CS203 | CS |
| ME498 | Senior Project | 12 | 12 | 4/Spring |  | MEE |
| Total |  | 65 | 31 |  |  |  |

## Curriculum Structure of Robotics Engineering

General Education
Courses (79)

Chinese Language and
Culture Module (16)
Arts and Physical Educatio
Module (6)
Physical Education, Arts
Competence Development Module (21)
Computer Programming,
Writing,
Chinese Studies,
Foreign Languages

## Humanities and Social

Sciences Module (6)
Humanities,
Social Sciences
Mathematics and Natural Sciences Module (28)
Mathematics
Physics,
Chemistry,
Biology
Introduction to Majors Modul (2)

| CAD and Engineering Drawing | Robot Modeling and Control |
| :---: | :---: |
| Fundamentals of Electric Circuits | Mechanical Design |
| Awareness Practice of Manufacturing Engineering |  |
|  | Machinery and Mechanical Design Labs |
| Engineering Mechanics <br> I - Statics and Dynamics |  |
|  | Robotic Actuation System |
| Signals and Systems |  |
| Probability and Statistics | Sensing Technologies |
| Fundamentals of Control Engineering |  |
| Materials Mechanics in Mechanical Engineering | Mechatronic Systems |
| Principles of Machinery | Machine Learning for Engineering |

## Major Elective Courses* $(\geq 15)$

- Robot Operating System
- C/C++ Program Desig
- Didgital Circuits
- Fundamentals and practices of project

$$
\begin{gathered}
\text { managememt } \\
\text { Analoo Circuit }
\end{gathered}
$$

- Data Structures and Algorithm Analysis B
- Mechanisms and Applications
- Walking Robot
Computer Visio
Dynamics and Vibration
ndamentals of Manufacturing
- Product Design Practice
Finite Element Theory and Its Engineering Applications
- Collaborative Robot Learning
- Microrobotics
- Advanced Kinematics and Dynamics of Mechanisms
- Modern Control and Estimation
Fundamentals of Engineering Optimization
- Microfabrication and Microsystems
- Soft Robotics
- Intelligent Robotics
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## Practice \& Internship

Note*: Major Elective Courses only list some courses, all courses are detailed in the program.

