# Department of Mechanical and Energy Engineering 

## Program of Robotics Engineering for International Students (2020)

## I. Introduction

Robotics Engineering is an interdisciplinary program that integrates the learning of mechanical, electronic and computer technologies. The aim of the program is to cultivate leading talents with solid scientific foundation, excellent innovative practical ability and broad international vision, who are good at comprehensive application of theories and methods of robotics and related disciplines, and who can solve engineering problems with the latest scientific development for the future. In terms of research, its directions cover industrial robots, robot software, bionic robots, medical robots, field robots, microrobots and emerging frontier areas of science and technology such as artificial intelligence, autonomous system, service future demand for the forefront of technology and basic industries, supporting the national economic development plan and Shenzhen's local informatization, intellectualization and manufacturing comprehensive upgrade a long-term positive impact.

## II. Objectives and Learning Outcomes

This program bases its objectives on the future development of robotics engineering and serves the human resource demand of the field in the background of the national mid and long term development planning. The program is committed to fostering students with a solid scientific foundation, excellent innovation capacity, broad international vision, integrated use of robotics theories and related disciplines, and skills of solving the engineering problems for the future with the latest science development.

Graduates of the program will be equipped with the following knowledge, capability, and accomplishment.

1. Solid and broad basic theoretical knowledge (including mathematics, physics, machinery, automation, electronics, computer, etc.), as well as subject knowledge in robot engineering;
2. Master the robotics theories, research and engineering design methods of robot engineering, and have a good knowledge of engineering technology and frontier development of the industry. Robotics Engineering is a multidisciplinary and interdisciplinary program and foster its students to become leading cross-disciplinary talents for the future.
3. Develop students with rigorous and practical attitude toward science and research, engagement in pursuing excellence, a strong sense of social responsibility and mission, and good communication skills;
4. Develop students with innovative thinking and the ability to independently identify, understand and solve problems in the real world with the application of robotics via the learning of the program;
5. Develop the international outlook and skills of communication and collaboration with international professionals of the related industry.

## III. Study Length and Graduation Requirements

Study length: 4 years. A 3-6 years of flexible study length is applied.
Degree conferred: Bachelor of Engineering for students fulfilling the requirements of the undergraduate program.

The minimum credit requirement for graduation: 130 credits (not including English courses);

| Category | Module | Minimum Credit Requirement |
| :---: | :---: | :---: |
| $\begin{gathered} \text { General Education (GE) } \\ \text { Required Courses } \\ (48 \text { creidts) } \\ \hline \end{gathered}$ | Science | 28 |
|  | Physical Education | 4 |
|  | Chinese Languages \& Culture | 16 |
| General Education (GE) Elective Courses (16 creidts) | Humanities | 4 |
|  | Social Sciences | 4 |
|  | Arts | 2 |
|  | Science | 6 |
| Major Course (66 creidts) | Major Foundational Courses | 26 |
|  | Major Core Courses | 12 |
|  | Major Elective Courses | 15 |
|  | Research Projects, Internship and Undergraduate Thesis / Projects | 13 |
| Total (not including English courses) |  | 130 |

## IV. Discipline

Robotics Engineering (080803T)

## V. Main Courses

Fundamental Courses of Engineering: Fundamentals of Electric Circuits, CAD and Engineering Drawing,, Engineering Mechanics I - B, Mechanics of Materials, Signals and Systems, Probability and Statistics, Fundamentals of Control Engineering, etc.

Core Courses of Robotics Engineering: Fundamentals of Machine Design, Robot Modeling and Control, Actuation System for Robotics, Sensors and Actuators, Pattern Recognition, Machine Learning, Artificial Intelligence, Mechatronic Systems, etc.

Special Courses of Robotics Engineering: Microrobotics, Walking Robot, Soft Robot, Collaborative Robot Learning, Microfabrication and Microsystems, Autonomous Robotic Systems, etc.

## VI. Practice-Based Courses

Engineering Training, Experiments, Course Projects, Practice I \& II, Innovation and Entrepreneurship, Senior Project, etc.

## VII. Pre-requisites for Major Declaration

| Major Declaration Time | Course <br> Code | Course Name | Prerequisite |
| :---: | :---: | :---: | :---: |
| Declare major at the end of First Year | MA101B | Calculus I A | NA |
|  | MA102B | Calculus II A | MA101B |
|  | PHY103B | General Physics B (I) | NA |
|  | PHY105B | General Physics B (II) | PHY103B |
|  | MA107A | Linear Algebra A* | NA |
|  | CS102B | Introduction to Computer Programming B* | NA |
|  | CH101B | General Chemistry B* | NA |
|  | Notes: <br> 1. At least one of those four courses (marked with *) should be passed. <br> 2. The above courses are the minimum requirements. The high-level courses are also acceptable. |  |  |
| Declare major at the end of Second Year | MA102B | Calculus II A | MA101B |
|  | PHY105B | General Physics B (II) | PHY103B |
|  | MA107A | Linear Algebra A | NA |
|  | CS102B | Introduction to Computer Programming B | NA |
|  | EE104 | Fundamentals of Electric Circuits | MA101B, MA107B |
|  | MAE203B | Engineering Mechanics I-Statics and Dynamics | MA107B |
|  | EE205 | Signals and Systems | NA |
|  | ME307 | Fundamentals of Control Engineering | EE104 |
|  | Notes: The above courses are the minimum requirements. The high-level courses are also acceptable. |  |  |

## VIII. Requirements for GE Required Courses

## (I) Science Module

| Course |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Code |$\quad$ Course Name

## (II) Physical Education

| Course Code | Course Name | $\begin{aligned} & \text { ? } \\ & \stackrel{0}{\infty} \\ & \stackrel{\rightharpoonup}{\hbar} \end{aligned}$ |  | $\stackrel{-1}{\text { ¢ }}$ |  |  | Dept. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GE131 | Physical Education I | 1 | 2 | Fall | C | NA | PE Center |
| GE132 | Physical Education II! | 1 | 2 | Spr | C | NA |  |
| GE231 | Physical Education III | 1 | 2 | Fall | C | NA |  |
| GE232 | Physic Education IV | 1 | 2 | Spr | C | NA |  |
| GE331 | Physical Education V | 0 | 1 | Fall | C | NA |  |
| GE332 | Physical Education VI | 0 | 1 | Spr | C | NA |  |
| GE431 | Physical Education VII | 0 | 1 | Fall | C | NA |  |
| GE432 | Physical Education VIII | 0 | 1 | Spr | C | NA |  |
|  | Total | 4 | 8 |  |  |  |  |

Note: All physical education courses are general required courses. For Semester 1-4, each
course(GE131.GE132,GE231,GE232) counted as 1 credit ; for semester 5-8, (GE331.GE332,GE431,GE432) are extracurriculum courses without no credits, details can be referred to Physical Education Curriculum Program of Sustech.
(III) Chinese Languages \& Culture


## (IV) English Language

Students will undertake the English Placement Test and be placed into three levels according to the result of the test and their performance in the National College Entrance Exam. Students at different levels are required to take the courses with a different credit value in total.

Level A: 6 credits; SUSTech English III, and English for Academic Purposes
Level B: 10 credits; SUSTech English II, SUSTech English III, and English for Academic Purposes
Level C: 14 credits; SUSTech English I, SUSTech English II, SUSTech English III, and English for Academic Purposes.

| Course Code | Course Name | $\begin{aligned} & \text { 윻 } \\ & \stackrel{2}{7} \end{aligned}$ |  |  |  | Dept |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CLE021 | SUSTech English I | 4 | 4 | E | NA | CLE |
| CLE022 | SUSTech English II | 4 | 4 | E | CLE021 |  |
| CLE023 | SUSTech English III | 4 | 4 | E | CLE022 |  |
| CLE030 | English for Academic Purposes | 2 | 2 | E | CLE023 |  |

## IX Requirements for GE Elective Courses

(I) Students are required to complete 4 credits for the Humanities Module and Social Sciences Module respectively, and 2 credits for the Music and Art Module. (Information about the available courses and the instruction language will be announced before the course selection session)
(II) Students are required to complete 6 credits for Science Module

| Course Code | Course Name | $\begin{aligned} & \text { O } \\ & \stackrel{\text { D}}{\#} \end{aligned}$ |  |  | $\begin{aligned} & \stackrel{\text { No }}{3} \\ & \hline \end{aligned}$ |  |  | 蒿 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BIO102B | Introduction to Life Science | 3 |  | 3 | 1/Spr/Fall | E | NA | BIO |
| CS205 | C/C++ Program Design | 3 | 1 | 4 | 2/Fall | B | NA | CSE |
| EE201-17 | Analog Circuits | 3 |  | 3 | 2/Fall | B | PHY105B, EE104 | EE |
| EE202-17 | Digital Circuits | 3 |  | 3 | 2/Spr | B | PHY105B, <br> EE201-17 | EE |
| MA201b | Ordinary Differential Equation B | 4 | 1 | 5 | 2/Spr | B | MA102B | MA |
| MA206 | Mathematics Modelling | 3 | 1 | 4 | 2/Spr | B | MA201b | MA |
|  | Total | 19 | 3 | 22 |  |  |  |  |

## X. Major Course Arrangement

Table 1: Major Required Course (Foundational and Core Courses)

|  | Course Code | Course Name |  |  |  |  |  |  |  | $\begin{aligned} & \text { 䓦 } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | EE104 | Fundamentals of Electric Circuits | 2 |  | 2 | Spr | 1/Spr | C/E | MA101B, MA107B | EE |
|  | ME102 | CAD and Engineering Drawing | 3 | $\begin{gathered} 1 . \\ 5 \end{gathered}$ | 4.5 | Fall/ <br> Spr/ <br> Smr | 1/Smr | B/E | NA | MEE |
|  | ME103 | Awareness Practice of Manufacturing Engineering | 3 | 2 | 5 | Fall/ <br> Spr <br> /Smr | 2/Fall | B/E | NA | MEE |
|  | $\begin{gathered} \text { MAE20 } \\ 3 B \end{gathered}$ | Engineering Mechanics IStatics and Dynamics | 3 |  | 3 | Fall | 2/Fall | E | MA107B | MAE |
|  | EE205 | Signals and Systems | 3 | 1 | 4 | Fall | 2/Fall | B/E | MA101B | EE |
|  | MA212 | Probability and Statistics | 3 | 1 | 4 | Fall | 2/Fall | E | MA102B | MA |
|  | $\begin{gathered} \hline \text { MAE20 } \\ 2 \end{gathered}$ | Mechanics of Materials | 3 |  | 3 | Fall | 2/Fall | E | MA107A, MA102B | MAE |
|  | ME307 | Fundamentals of Control Engineering | 3 | $\begin{aligned} & \hline 0 . \\ & 5 \\ & \hline \end{aligned}$ | 3.5 | $\begin{aligned} & \text { Fall/ } \\ & \text { Spr } \end{aligned}$ | 2/Spr | B/E | EE104, MA201b | MEE |
|  | ME303 | Fundamentals of Machine Design | 3 | 1 | 4 | $\begin{aligned} & \text { Fall/ } \\ & \text { Spr } \end{aligned}$ | 2/Spr | B/E | MAE203B, <br> ME102, <br> MAE202 | MEE |
|  |  | Total | 26 | 7 | 33 |  |  |  |  |  |
| $\ddot{\oplus}$ | ME331 | Robot Modeling and Control | 3 |  | 3 | Fall | 3/Fall | B/E | MAE203B | MEE |
|  | $\begin{gathered} \text { EE423- } \\ 14 \end{gathered}$ | Pattern Recognition* | 3 | 1 | 4 | Fall | 3/Fall | B | $\begin{aligned} & \text { MA107A, } \\ & \text { EE205, } \\ & \text { MA212 } \\ & \hline \end{aligned}$ | EE |
|  | CS303B | Artificial Intelligence $\mathrm{B}^{*}$ | 3 | 1 | 4 | Fall | 3/Fall | B | CS101A, CS203B, MA212 | CS |
|  | CS405 | Machine Learning* | 3 | 1 | 4 | Fall | 4/Fall | B | MA107A, <br> MA212 | CS |
|  | ME321 | Sensors and Actuators** | 3 | 1 | 4 | Spr | 2/Spr | E | EE104 | MEE |
|  | ME322 | Actuation System for Robotics** | 3 | 1 | 4 | Fall | 3/Fall | E | MA102B | MEE |
|  | ME333 | Mechatronic Systems | 3 | 1 | 4 | Fall/ <br> Spr | 3/Spr | E | ME331 | MEE |
|  |  | Total | 21 | 6 | 27 |  |  |  |  |  |
| $\begin{aligned} & \text { To } \\ & \text { 啇 } \\ & \stackrel{\rightharpoonup}{\top} \end{aligned}$ | ME494 | Practice I | 1 | 1 | 2 |  |  |  |  | MEE |
|  | ME495 | Practice II | 2 | 2 | 4 |  |  |  |  | MEE |
|  | ME496 | Innovation and | 2 | 2 | 4 |  |  |  |  | MEE |


|  |  | Entrepreneurship: Practice <br> and Principles |  |  |  |  |  |  |  |  |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Table 2: Major Elective Courses

| Course Code | Course Name | $\begin{aligned} & \text { 울 } \\ & \stackrel{\text { Da }}{7} \end{aligned}$ |  |  | $\begin{aligned} & \stackrel{\rightharpoonup}{\mathrm{o}} \\ & \underset{3}{ } \end{aligned}$ |  |  |  | \% |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ME232 | Prolegomenon to Robotics | 3 |  | 3 | Spr | 1/Spr | E | NA | MEE |
| ME332 | Robot Operating System | 3 | 1 | 4 | Spr | 2/Spr | B | CS102B | MEE |
| CS203B | Date Structure and Algorithm Analysis B | 3 | 1 | 4 | Fall | 3/Fall | B | CS101A | CS |
| ME313 | Product Design Practice | 3 | 1 | 4 | Spr | 3/Spr | B | $\begin{gathered} \text { ME303 } \\ \text { or } \\ \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| ME312 | Advanced Kinematics and Dynamics of Mechanisms | 3 |  | 3 | Spr | 3/Spr | B | $\begin{aligned} & \text { ME306 } \\ & \text { or } \\ & \text { ME331 } \end{aligned}$ | MEE |
| ME301 | Dynamics and Vibration* | 3 | 1 | 4 | $\begin{aligned} & \hline \text { Fall/ } \\ & \text { Spr } \end{aligned}$ | 3/Spr | E | MAE203B, MA201b | MEE |
| ME302 | Fundamentals of Manufacturing | 3 |  | 3 | Fall/ <br> Spr | 3/Spr | E | ME103, ME303 | MEE |
| CS308 | Computer Vision | 3 | 1 | 4 | Spr | 3/Spr | B | 无 | CS |
| ME426 | Fundamentals of Engineering Optimization | 3 |  | 3 | Spr | 3/Spr | E | MA102B, MA107B | MEE |
| ME334 | Microrobotics | 3 |  | 3 | Spr | 3/Spr | E | ME307 | MEE |
| ME335 | Microfabrication and Microsystems | 3 |  | 3 | Spr | 3/Spr | E | PHY105B | MEE |
| ME336 | Collaborative Robot Learning | 3 | 1 | 4 | Spr | 3/Spr | E | $\begin{gathered} \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| ME434 | Walking Robot | 3 | 0.5 | 3.5 | Spr | 3/Spr | B | $\begin{gathered} \hline \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| ME314 | Finite Element Theory and Its Engineering Applications | 3 |  | 3 | Spr | 3/Spr |  | MAE202, MA107A | MEE |
| ME435 | Soft Robot | 3 |  | 3 | Fall | 4/Fall | B | ME303 | MEE |
| ME424 | Modern Control and Estimation | 3 |  | 3 | Fall | 4/Fall | E | ME307 | MEE |
| $\begin{gathered} \text { MEE511 } \\ 5 \end{gathered}$ | Autonomous Robitc Systems | 3 |  | 3 | Fall | 4/Fall | E | MA107A, MA212 | MEE |
| CS401 | Intelligent Robotics | 3 | 1 | 4 | Spr | 4/Spr | E | CS101A, CS203, CS202 | CS |
|  | Total | 54 | 7.5 | 61.5 |  |  |  |  |  |
| Notes: <br> 1. The minimum of 9 credits is required for the above courses. <br> 2. In addition, students are required to take optional courses under the guidance of tutors, with a minimum of 6 credits. <br> 3. *MAE314 Theory of Vibration can be identified as ME301 Dynamics and Vibration. |  |  |  |  |  |  |  |  |  |

Table 3: Overview of Practice-Based Courses

| Course Code | Course Name | $\begin{aligned} & \text { 잏 } \\ & \stackrel{0}{7} \end{aligned}$ |  |  | $\stackrel{\text { ¢ }}{3}$ |  |  |  | 帝 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ME102 | CAD and Engineering Drawing | 3 | 1.5 | 4.5 | Fall/ <br> Spr/ <br> Smr | 1/Smr | B/E | NA | MEE |
| ME103 | Awareness Practice of Manufacturing Engineering | 3 | 2 | 5 | $\begin{gathered} \hline \text { Fall// } \\ \mathrm{Spr} \\ \text { /Smr } \end{gathered}$ | 2/Fall | B/E | NA | MEE |
| EE205 | Signals and Systems | 3 | 1 | 4 | Fall | 2/Fall | B/E | MA101B | EE |
| MA212 | Probability and Statistics | 3 | 1 | 4 | Fall | 2/Fall | E | MA102B | MA |
| ME307 | Fundamentals of Control Engineering | 3 | 0.5 | 3.5 | $\begin{aligned} & \hline \text { Fall/ } \\ & \mathrm{Spr} \\ & \hline \end{aligned}$ | 2/Spr | B/E | $\begin{aligned} & \hline \text { EE104, } \\ & \text { MA201b } \end{aligned}$ | MEE |
| ME303 | Fundamentals of Machine Design | 3 | 1 | 4 | Fall/ Spr | 2/Spr | B/E | MAE203B, <br> ME102, <br> MAE202 | MEE |
| $\begin{gathered} \text { EE423-1 } \\ 4 \end{gathered}$ | Pattern Recognition | 3 | 1 | 4 | Fall | 3/Fall | B | MA107A, EE205, ,MA212 | EE |
| CS303B | Artificial Intelligence B | 3 | 1 | 4 | Fall | 3/Fall | B | CS101A, CS203B, MA212 | CS |
| CS405 | Machine Learning | 3 | 1 | 4 | Fall | 4/Fall | B | MA107A, MA212 | CS |
| ME321 | Sensors and Actuators | 3 | 1 | 4 | Spr | 2/Spr | E | EE104 | MEE |
| ME322 | Actuation System for Robotics | 3 | 1 | 4 | Fall | 3/Fall | E | MA102B | MEE |
| ME333 | Mechatronic Systems | 3 | 1 | 4 | $\begin{aligned} & \hline \text { Fall// } \\ & \mathrm{Spr} \\ & \hline \end{aligned}$ | 3/Spr | E | ME331 | MEE |
| ME332 | Robot Operating System | 3 | 1 | 4 | Spr | 2/Spr | B | CS102B | MEE |
| CS203B | Date Structure and Algorithm Analysis B | 3 | 1 | 4 | Fall | 3/Fall | B | CS101A | CS |
| ME313 | Product Design Practice | 3 | 1 | 4 | Spr | 3/Spr | B | $\begin{gathered} \text { ME303 } \\ \text { or } \\ \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| ME301 | Dynamics and Vibration* | 3 | 1 | 4 | $\begin{aligned} & \hline \text { Fall/ } \\ & \mathrm{Spr} \\ & \hline \end{aligned}$ | 3/Spr | E | MAE203B, MA201b | MEE |
| CS308 | Computer Vision | 3 | 1 | 4 | Spr | 3/Spr | B | 无 | CS |
| ME336 | Collaborative Robot Learning | 3 | 1 | 4 | Spr | 3/Spr | E | $\begin{gathered} \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| ME434 | Walking Robot | 3 | 0.5 | 3.5 | Spr | 3/Spr | B | $\begin{gathered} \text { ME306 } \\ \text { or } \\ \text { ME331 } \end{gathered}$ | MEE |
| CS401 | Intelligent Robotics | 3 | 1 | 4 | Spr | 4/Spr | E | CS101A, CS203, CS202 | CS |


| ME494 | Practice I | 1 | 1 | 2 |  |  |  |  | MEE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ME495 | Practice II | 2 | 2 | 4 |  |  |  |  | MEE |
| ME496 | Projects of Innovation and <br> Entrepreneurship | 2 | 2 | 4 |  |  |  |  | MEE |
| ME493 | Senior Project | 8 | 8 | 16 |  |  |  |  | MEE |
|  | Total | 73 | 33.5 | 10.65 |  |  |  |  |  |

Table 4: Overview of Course Hours and Credits

| Course Category | Total Course <br> Hours | Total Credits | Credit <br> Requirements | Percentage of the <br> Total $^{*}$ |
| :---: | :---: | :---: | :---: | :---: |
| General Education (GE) Required <br> Courses (not including English <br> courses) |  | 48 | $36.92 \%$ |  |
| General Education (GE) Elective <br> Courses |  | 16 | $12.31 \%$ |  |
| Major Foundational Courses | 528 | 26 | 26 | $20.00 \%$ |
| Major Core Courses | 432 | 21 | 12 | $9.23 \%$ |
| Major Elective Courses | 1000 | 54 | 15 | $11.54 \%$ |
| Research Projects, Internship <br> and Undergraduate Thesis/Projects | 416 | 13 | 13 | $10.00 \%$ |
| Total <br> (not including English courses) |  |  | 130 |  |

* Percentage of the total $=$ Credit requirements of each line / Total credit requirements


## Curriculum Structure of Robotics Engineering



Notes*: Elective Courses only list some courses, all courses are detailed in the program.

